## Loop Invariants and Binary Search

## Learning Outcomes

> From this lecture, you should be able to:
$\square$ Use the loop invariant method to think about iterative algorithms.
$\square$ Prove that the loop invariant is established.
$\square$ Prove that the loop invariant is maintained in the 'typical' case.
$\square$ Prove that the loop invariant is maintained at all boundary conditions.
$\square$ Prove that progress is made in the 'typical' case
$\square$ Prove that progress is guaranteed even near termination, so that the exit condition is always reached.
$\square$ Prove that the loop invariant, when combined with the exit condition, produces the post-condition.
$\square$ Trade off efficiency for clear, correct code.

## Outline

> Iterative Algorithms, Assertions and Proofs of Correctness
> Binary Search: A Case Study

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## Assertions

$\Rightarrow$ An assertion is a statement about the state of the data at a specified point in your algorithm.
$>$ An assertion is not a task for the algorithm to perform.
$>$ You may think of it as a comment that is added for the benefit of the reader.

## Loop Invariants

$>$ Binary search can be implemented as an iterative algorithm (it could also be done recursively).
> Loop Invariant: An assertion about the current state useful for designing, analyzing and proving the correctness of iterative algorithms.

## Other Examples of Assertions

> Preconditions: Any assumptions that must be true about the input instance.
> Postconditions: The statement of what must be true when the algorithm/program returns.
> Exit condition: The statement of what must be true to exit a loop.

## Iterative Algorithms

Take one step at a time towards the final destination

loop<br>take step<br>end loop

## Establishing Loop Invariant

From the Pre-Conditions on the input instance we must establish the loop invariant.


## Maintain Loop Invariant

$>$ Suppose that
$\square$ We start in a safe location (pre-condition)
$\square$ If we are in a safe location, we always step to another safe location (loop invariant)
> Can we be assured that the computation will always be in a safe location?
> By what principle?

## Maintain Loop Invariant

- By Induction the computation will always be in a safe location.



## Ending The Algorithm

> Define Exit Condition
Exit
> Termination: With sufficient progress, the exit condition will be met.
> When we exit, we know
$\square$ exit condition is true

- loop invariant is true
from these we must establish the post conditions.



## Definition of Correctness

## <PreCond> \& <code> $\rightarrow$ <PostCond>

If the input meets the preconditions,
then the output must meet the postconditions.

If the input does not meet the preconditions, then nothing is required.

## End of Lecture

## MAR 12, 2015

## Outline

> Iterative Algorithms, Assertions and Proofs of Correctness
> Binary Search: A Case Study

## Define Problem: Binary Search

> PreConditions
CKey 25
$\square$ Sorted List

| 3 | 5 | 6 | 13 | 18 | 21 | 21 | 25 | 36 | 43 | 49 | 51 | 53 | 60 | 72 | 74 | 83 | 88 | 91 | 95 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

> PostConditions
$\square$ Find key in list (if there).

| 3 | 5 | 6 | 13 | 18 | 21 | 21 | 25 | 36 | 43 | 49 | 51 | 53 | 60 | 72 | 74 | 83 | 88 | 91 | 95 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

## Define Loop Invariant

> Maintain a sublist.
$>$ If the key is contained in the original list, then the key is contained in the sublist.
key 25

| 3 | 5 | 6 | 13 | 18 | 21 | 21 | 25 | 36 | 43 | 49 | 51 | 53 | 60 | 72 | 74 | 83 | 88 | 91 | 95 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

## Define Step

$>$ Cut sublist in half.
$>$ Determine which half the key would be in.
$>$ Keep that half.


## Define Step

$>$ It is faster not to check if the middle element is the key.
$>$ Simply continue.


## Make Progress

$>$ The size of the list becomes smaller.



## Exit Condition


> If the key is contained in the original list,
then the key is contained in the sublist.
> Sublist contains one element.

- If element = key, return associated entry.
- Otherwise return false.


## Running Time

## The sublist is of size $n, n / 2, n / 4, n / 8, \ldots, 1$

Each step $O(1)$ time.
Total = O(log n)


## Running Time

$>$ Binary search can interact poorly with the memory hierarchy (i.e. caching), because of its random-access nature.
$>$ It is common to abandon binary searching for linear searching as soon as the size of the remaining span falls below a small value such as 8 or 16 or even more in recent computers.

## BinarySearch(A[1..n],key)

<precondition»: A[1..n] is sorted in non-decreasing order
<postcondition>: If key is in A[1..n], algorithm returns its location

$$
p=1, q=n
$$

while $q>p$
< loop-invariant>: If key is in A[1..n], then key is in A[p..q]
mid $=\left\lfloor\frac{p+q}{2}\right\rfloor$
if key $\leq A$ [mid]

$$
q=\operatorname{mid}
$$

else

$$
p=m i d+1
$$

end
end
if key $=A[p]$
return( $p$ )
else
return("Key not in list")
end

## Simple, right?

$>$ Although the concept is simple, binary search is notoriously easy to get wrong.
$>$ Why is this?


## Boundary Conditions

$>$ The basic idea behind binary search is easy to grasp.
$>$ It is then easy to write pseudocode that works for a 'typical' case.
> Unfortunately, it is equally easy to write pseudocode that fails on the boundary conditions.

## Boundary Conditions

```
if key \(\leq A[\) mid \(]\)
        \(q=\operatorname{mid}\)
else
    \(p=m i d+1\)
end
```



## What condition will break the loop invariant?

## Boundary Conditions



Code: key $\geq A[$ mid $] \rightarrow$ select right half
Bug!!

## Boundary Conditions

```
if key \leqA[mid]
\[
q=\operatorname{mid}
\]
else
\[
p=\operatorname{mid}+1
\]
end
```

if key < A [mid ]
$q=\operatorname{mid}-1$
else
$p=\operatorname{mid}$
end


Not OK!!

## Boundary Conditions

$$
\operatorname{mid}=\left\lfloor\frac{p+q}{2}\right\rfloor \quad \text { or } \quad \operatorname{mid}=\left\lceil\frac{p+q}{2}\right\rceil
$$



Shouldn't matter, right? Select mid $=\left\lceil\frac{p+q}{2}\right\rceil$

## Boundary Conditions

$$
\begin{aligned}
& \text { if key } \leq A[\mathrm{mid}] \\
& \quad q=\text { mid } \\
& \text { else } \\
& \quad p=\text { mid }+1 \\
& \text { end }
\end{aligned}
$$

Select mid $=\left\lceil\frac{p+q}{2}\right\rceil$

If key $\leq$ mid, then key is in
left half.

Prof. J. Elder

If key > mid, then key is in right half.

## Boundary Conditions

$$
\begin{aligned}
& \text { if key } \leq A[\text { mid }] \\
& q=\text { mid } \\
& \text { else } \\
& \quad p=\text { mid }+1 \\
& \text { end }
\end{aligned}
$$



## Boundary Conditions

$$
\text { if key } \leq A[\mathrm{mid}]
$$

$$
q=\mathrm{mid}
$$

else

$$
p=\text { mid }+1
$$

end

No progress
toward goal:

- Another bug! $\overbrace{}^{?}$ Loops Forever!

$$
\text { Select mid }=\left\lceil\frac{p+q}{2}\right\rceil
$$

If key $\leq$ mid, $\quad$ If key $>$ mid, then key is in then key is in left half. right half.

## Boundary Conditions

| mid $=\left\lfloor\frac{p+q}{2}\right\rfloor$ | mid $=\left\lceil\frac{p+q}{2}\right\rceil$ |
| :--- | :--- |
| if key $\leq A[\mathrm{mid}]$ | if key $<A[\mathrm{mid}]$ |
| $q=$ mid | $q=\mathrm{mid}-1$ |
| else | else |
| $\quad p=$ mid +1 | $p=$ mid |
| end | end |



Not OK!!

## Getting it Right

> How many possible algorithms?
> How many correct algorithms?
> Probability of guessing correctly?

## Alternative Algorithm: Less Efficient but More Clear

```
BinarySearch(A[1..n], key)
<precondition>: A[1..n] is sorted in non-decreasing order
<postcondition>: If key is in A[1..n], algorithm returns its location
p=1,q=n
while q\geqp
    <loop-invariant>: If key is in A[1..n], then key is in A[p..q]
    mid =\\frac{p+q}{2}\rfloor
    if key < A[mid]
        q=mid -1
    else if key > A[mid]
        p=mid +1
    else
        return(mid)
    end
end
return("Key not in list")
```


## Assignment 3 Q2: kth Smallest of Union

$>\mathrm{e}=\mathrm{kth}$ SmallestOfUnion(k)
$\square$ e.g., kthSmallestOfUnion(6) $=7$
$>$ Observation: e must be in first k positions of A 1 or A 2 , i.e., $e \in A_{1}[0 \ldots k-1] \cup A_{2}[0 \ldots k-1]$
$>\rightarrow$ Step 1: Truncate A1 and A2 to length $k$.

| A1 | 1 | 2 | 5 | 7 | 10 | 16 | 18 |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | A2 | 3 | 4 | 8 | 9 | 11 | 12 | 14 |

## Assignment 3 Q2: kth Smallest of Union

$>\mathrm{e}=\mathrm{kth}$ SmallestOfUnion(k)
$\square$ e.g., kthSmallestOfUnion(6) $=7$
> Step 2: Divide and Conquer!
$\square$ Case 1: A1[2] > A2[2]. In what intervals must the kth smallest lie?
$\square$ Case 2: A1[2] < A2[2]. In what intervals must the kth smallest lie?


## Assignment 3 Q2: kth Smallest of Union

> More generally: maintain the loop invariant that the kth smallest key is stored in

$$
A_{1}\left[k_{1 l} \ldots k_{1 u}\right] \cup A_{2}\left[k_{2 l} \ldots k_{2 u}\right]
$$



## Assignment 3 Q2: kth Smallest of Union

$>$ Now bisect $\mathrm{A}_{1}: \quad k_{1}=\left\lfloor\left(k_{1 l}+k_{1 u}\right) / 2\right\rfloor$ and define $k_{2}=k-k_{1}-1$.
$\Rightarrow$ Note that $k_{1}+k_{2}=k-1$
$>$ Now compare $A_{1}\left[k_{1}\right]$ and $A_{2}\left[k_{2}\right]$.
> What sub-intervals can you safely rule out?
$>$ Now update $k_{1 l}, k_{1 u}, k_{2 l}, k_{2 u}$ accordingly, and iterate!


## Assignment 3 Q2: kth Smallest of Union

> To simplify the problem, assume that original input arrays are of the same length.
$>$ Note that $\mathrm{k}<2 \mathrm{n}$, or a RankOutOfRangeException is thrown.


Compare (A1[2], A2[2])

## Assignment 3 Q2: kth Smallest of Union

$>$ What if $\mathrm{k}<\mathrm{n}$ ?
$>$ Then we first truncate both arrays to be of length k .


## Assignment 3 Q2: kth Smallest of Union

$>$ What if $\mathrm{k}>\mathrm{n}$ ?
$>$ Then we first trim the tails of the arrays so they are of length k .


## Assignment 3 Q2: kth Smallest of Union

$>$ What if $\mathrm{k}>\mathrm{n}+1$ ?
$>$ Then we first trim the beginning of both arrays so they are of length $n-(k-n-1)+1=2 n-k+1$.


## Assignment 3 Q2: kth Smallest of Union

$>$ Thus at the beginning of the loop, we have the kth smallest element in

$$
A_{1}\left[k_{1 l} \ldots k_{1 u}\right] \cup A_{2}\left[k_{2 l} \ldots k_{2 u}\right]
$$



## Assignment 3 Q2: kth Smallest of Union

$>$ Now let $k_{1}=\left\lceil\left(k_{1 l}+k_{1 u}\right) / 2\right\rceil$ and $k_{2}=\left\lfloor\left(k_{2 l}+k_{2 u}\right) / 2\right\rfloor$
$>$ Then we have that $k_{1}+k_{2}=k-1$.
$>$ In the loop we will compare $A_{1}\left[k_{1}\right]$ and $A_{2}\left[k_{2}\right]$, and update, while preserving 3 loop invariants:
$>\quad / / \mathrm{LI} 1: \mathrm{kth}$ smallest is in A1[k11...k1u] or A2[k2I...k2u]
//LI2: $k 1+k 2=k-1$
//LI3: $|\mathrm{n} 1-\mathrm{n} 2|<2$

$A_{2} \mathrm{l}$

## Card Trick



## Pick a Card



## Done

Thanks to J. Edmonds for this example.

## Loop Invariant: The selected card is one of these.



## Which column?



## left

## Loop Invariant: The selected card is one of these.



## Selected column is placed in the middle



## I will rearrange the cards



## Relax Loop Invariant: I will remember the same about each column.



## Which column?



## right

## Loop Invariant: The selected card is one of these.



## Selected column is placed in the middle



## I will rearrange the cards



## Which column?



## left

## Loop Invariant: The selected card is one of these.



## Selected column is placed in the middle




## Wow!

## Ternary Search

> Loop Invariant: selected card in central subset of cards

$$
\begin{aligned}
& \text { Size of subset }=\left\lceil n / 3^{i-1}\right\rceil \\
& \text { where } \\
& n=\text { total number of cards } \\
& i=\text { iteration index }
\end{aligned}
$$

> How many iterations are required to guarantee success?

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Trade off efficiency for clear, correct code.

